

Breaking the Surface 2021

Biograd na Moru, Croatia 26th September-3rd October

PROCEEDINGS

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1. INTRODUCTION

The Breaking the Surface 2021 was held from 26th September until 3rd October in Biograd na Moru, Croatia and more than 130 people participated. It was the first, successful, post-pandemic edition of Breaking the Surface (Bts), the international interdisciplinary workshop on robotics and maritime innovations organized by the Faculty of Electrical and Computer Engineering (FER) of the University of Zagreb. The programme was divided in three tracks (marine robotics, maritime archeology, marine biology) and included 20 in-depth lectures, 7 tutorials, 5 demos and a full day workshop on Analysis Of Data From Marine Observatories.

Dates: 26th September – 3rd October 2021

Location: Biograd na Moru, Croatia

Website: http://bts.fer.hr/

2. REPORT ORGANIZATION

The first part of the report describes the BtS 2021 organization, including the work program. The deliverable is accompanied with abstracts, biographies, and presentations of the program presenters:

3. ABOUT BREAKING THE SURFACE

Breaking the Surface - BtS summer school has been organized by UNIZG FER LABUST for the last 12 years – first three years as a part of FP7-REGPOT CURE project, while in the following years with Office of Naval Research Global and EU funded projects. This year's BTS was financed and supported by Interreg Italy-Croatia InnovaMare project, H2020 EUMarine Robots – Marine Robotics Research Infrastructure Network and IEEE Oceanic Engineering Society. During the years, BtS served as a meeting place of experts and students of marine robotics and the marine robotics application areas such as marine biology, marine archaeology, marine security, oceanography, marine geology, and oceanology. This is the world's first successful, multi-year field training programme that combines academic topics in marine robotics and robotics application areas and hands-on working experience in the sea, doing remote sensing and sampling for various ocean sciences.

The program is organized in the form of plenary talks, hands-on tutorials and demonstrations of marine technologies, e.g. marine robotics (MAROB, marine biology and marine nature protection (MARBIO), maritime, nautical and ship archaeology (MARCH), oceanography (OCEAN), and company presentations

BTS2021 IN NUMBERS:













TUTORIALS

5 DEMOS

WORKSHOP

4. ORGANIZERS

Breaking the Surface is organized under the European Union's Horizon 2020 project EUMarineRobots – Marine Robotics Research Infrastructure Network (GA: 731103), Interreg Italy-Croatia InnovaMare project (ID: 10248782), and IEEE Oceanic Engineering Society. The main organizers are University of Zagreb Faculty of Electrical Engineering and Computing, Laboratory for Underwater Systems and Technologies and Centre for Underwater Systems and Technologies University of Zagreb Faculty of Electrical Engineering and Computing.

ORGANIZERS









University of Zagreb

Faculty of Electrical Engineering and Computing Laboratory for Underwater Systems and Technologies Centre for Underwater Systems and Technologies

IN PARTNERSHIP WITH







AMOS – Centre for Autonomous Marine Operations and Systems

Associação do Instituto Superior Técnico para a Investigação e Desenvolvimento

Distretto Ligure delle Tecnologie Marine







Herriot Watt University

Institut Français de Recherche pour l'exploitation de la Mer

Integrated Systems for Marine Enviroment







Jacobs University

King's College London

Marine Institute Foras na Mara







Norwegian University of Science and Technology (NTNU)

NATO S&T Centre for Maritime Research and Experimentation

National Technical University of Athens







Natural Environment Research Council

Tallinn University of Technology

The Oceanic Platform of the Canary Islands



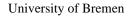




The Association of Instituto Superior Técnico for Research and Development



Universidade de Lisboa (ULisboa)







University of Girona (UdG)

University of Limerick (UL)

University of Porto

BREAKING THE SURFACE ORGANIZATION STRUCTURE:

4.1. COMMITTEES CHAIRS



Prof. Dr. Sc. Zoran Vukić General Chair

University of Zagreb,
Faculty of Electrical
Engineering and
Computing,
Laboratory for Underwater
Systems and Technologies



Prof. Dr. Sc. Nikola Mišković Programme Committee Chair

University of Zagreb,
Faculty of Electrical
Engineering and
Computing,
Laboratory for Underwater
Systems and Technologies



Ana Golec, Organizing Committee Chair

University of Zagreb,
Faculty of Electrical
Engineering and
Computing,
Laboratory for Underwater
Systems and Technologies



Igor Kvasić, Technical Committee Chair

University of Zagreb,
Faculty of Electrical
Engineering and
Computing,
Laboratory for Underwater
Systems and Technologies

4.2. PROGRAMME COMMITTEE



Prof. João Sousa

University of Porto

Portugal



Roee Diamant

University of Haif

Israel



Massimo Caccia

Italian National Research Council (CNR)

Italy



Ralf Bachmayer

University of Bremen

Germany



Prof. Bridget Buxton, PhD

University of Rhode Island

USA



Bill Kirkwood

Monterey Bay Aquarium Research Institute (MBARI)

USA



Fausto Ferreira

UNIZG FE

Croatia



Irena Radić Rossi

University of Zadar

Croatia

4.3. ORGANIZING COMMITTEE



Ana Golec UNIZG LABUST

4.4. TECHNICAL COMMITTEE



Anja Babić, mag. ing.

UNIZG FER LABUST



mag. ing.

UNIZG FER LABUST



Nikica Kokir

UNIZG FER LABUST



Ivan Lončar, mag. ing.

UNIZG FER LABUST



Igor Kvasić, mag. ing.

UNIZG FER LABUST



Đula Nađ, dipl. ing.

UNIZG FER LABUST

5. PROGRAMME

5.1. PROGRAMME STRUCTURE

BtS program consists of academic lectures, hands-on tutorials, presentation of projects and equipment, company demonstrations and social activities











5.1.1. PROGRAMME ABSTRACTS, BIOGRAPHIES AND PRESENTATIONS

The daily lecture programme follows below with the list of talks and speakers and links to the abstracts, biographies, a workshop, and video recordings.

Monday, 27th September

09:15 – 10:00 ROBOTS FOR KARSTIC EXPLORATION by LIONEL LAPIERRE

10:00 – 10:45 LEVERAGING OCEAN DATA HARVESTING BY HETEROGENOUS ROBOTIC ORGANIZATIONS AND AUTONOMOUS VEHICLES AS SENSOR CARRYING PLATFORMS by ASGEIR J. SØRENSEN, JENS EINAR BREMNES

11:00 – 11:45 LOW COST DOES NOT COME CHEAP: WORKING TOWARDS A LOW COST DEEP-SEA AUTONOMOUS OBSERVATION SYSTEM by RALF BACHMAYER

11:45 – 12:30 TITANIC REVISITED by BRIDGET BUXTON

12:30 – 13:15 PRESENT STATUS AND ACHIEVEMENTS AT THE SWEDISH MARITIME ROBOTICS CENTRE SMARC – AN INVITATION TO COLLABORATE by IVAN STENIUS

Tuesday, 28th September

09:00 – 09:45 WHALING IN THE EUROPEAN ARCTIC 1600-1900 – TECHNOLOGICAL INNOVATION AND ADAPTATION by ØYVIND ØDEGÅRD

09:45 – 10:30 MAKING SENSE OF MARINE AND MARITIME PROCESSES THROUGH INTELLIGENT INFORMATION ACQUISITION AND SHARING by IOANNIS KYRIAKIDES

10:45 – 11:30 MULTIDISCIPLINARY APPLICATIONS OF ROBOTIC SOLUTIONS IN SHALLOW COASTAL ENVIRONMENTS by FRANCESCA DE PASCALIS, FANTINA MADRICARDO

11:30 – 12:15 FORMAL AND RISK-BASED METHODS FOR DESIGNING, TESTING AND VERIFYING AUTONOMOUS MARINE CONTROL SYSTEMS by RENAN G. MAIDANA, TOBIAS R. TORBEN, THOMAS JOHANSEN, ASGEIR J. SØRENSEN

12:15 – 13:00 UNDERWATER ARCHAEOLOGY AT BTS: A DECADE OF INNOVATION by JACOB SHARVIT, BRIDGET BUXTON

12:15 – 13:00 MARINE UNITY SIMULATOR by IVAN LONČAR, JURAJ OBRADOVIĆ, LUKA MANDIĆ, NATKO KRAŠEVAC, NIKICA KOKIR, KRISTIJAN KRČMAR, MAK GRAČIĆ

Wednesday, 29th September

- 09:00 09:45 INNOVAMARE PROJECT by MATEO IVANAC, ANGELO ODETTI, FAUSTO FERREIRA
- 09:45 10:30 ADRIATIC by ĐULA NAĐ
- 10:45 11:30 UNDERWATER HUMAN ROBOT INTERACTION (U-HRI): AN OVERVIEW OF THE HISTORY, CHALLENGES, AND METHODS by ANDREAS BIRK
- 11:30 12:15 INFORMATIVE SPATIAL SAMPLING WITH AUTONOMOUS UNDERWATER VEHICLES by JO EIDSVIK
- 12:15 13:00 EXPLORATIONS IN AI FOR MARINE ROBOTICS by KANNA RAJAN

Thursday, 30th September

- 09:00 09:15 WORKSHOP: INTRODUCTION TO THE WORKSHOP THE CHALLENGE OF DATA PROCESSING FROM MARINE OBSERVATORIES by ROEE DIAMANT
- 09:15 09:30 WORKSHOP: INTRODUCTION TO THE WORKSHOP THE NEED FOR STANDARDIZATION IN MARINE OBSERVATORIES by NUNO ALEXANDRE CRUZ
- 09:30 10:15 WORKSHOP: MANAGEMENT AND PROCESSING OF GEOPHYSICAL DATA FROM CONTINUOUS MONITORING ONBOARD THE SHIP NRP SAGRES by SUSANA BARBOSA
- 11:00 11:45 WORKSHOP: QUALITY ASSURANCE FOR DATA FROM THE THEMO MARINE OBSERVATORY by ROEE DIAMANT
- 11:45 12:30 WORKSHOP: USING AUVS FOR IN-SITU CALIBRATION OF SENSORS ONBOARD MARINE OBSERVATORIES by NUNO ALEXANDRE CRUZ
- 14:30 15:00 WORKSHOP: ODYSSEA OPERATING A NETWORK OF INTEGRATED OBSERVATORY SYSTEMS IN THE MEDITERRANEAN SEA by GEORGIOS SYLAIOS
- 15:00 15:30 WORKSHOP: NEW FINDINGS FROM THE DEEPLEV DEEPWATER MARINE OBSERVATORY by AYAH LAZAR
- 15:30 16:00 WORKSHOP: THEMO SCIENCE DISCOVERIES FROM THE FIRST THREE YEARS OF OBSERVATIONS by STEVE DIMARCO

Friday, 1st October

- 09:00 09:45 UNDERWATER HYPERSPECTRAL IMAGING AS A TOOL FOR BENTHIC HABITAT MAPPING by AKSEL ALSTAD MOGSTAD
- 09:45 10:30 DATA DRIVEN METHODS FOR DERIVING BATHYMETRIC MAPS FROM SIDE-SCAN SONARS by JOHN FOLKESSON

10:45 – 11:30 AN ROV REVOLUTION? USING THE NEW GENERATION OF LOW-COST BATTERY POWERED ROVS FOR SUBSEA ARCHAEOLOGICAL WORK by GRAHAM SCOTT

11:30 - 12:15 ROBOTIC SYSTEMS IN MARICULTURE by NIKŠA GLAVIĆ, NENAD ANTOLOVIĆ

12:15 – 13:00 ACCURATE QLBL ACOUSTIC POSITIONING OF MULTIPLE, FAST MOVING UNDERWATER TARGETS IN CONFINED WATERS by OLEKSIY KEBKAL

VIDEO PRESENTATIONS

The morning lectures were recorded and were made available to the public on YouTube LABUST channel: https://www.youtube.com/user/LABUSTunizg.

5.2. SCHEDULE

The table below summarizes the schedule available at https://bts.fer.hr/schedule-2021/

| | MON, 27.09. | | | TUE,28.09. | | | | WED, 29.09. | | | | THU, 30.09. | | | | FRI, 01.10. | | | | | |
|---------------|--|-----------|-------------|--|--|----------------------------|-----------------|-----------------------|---|------------------------------|---------|--|--|-----------------------------|---|--|-------------------------------------|---------|----------|---|--|
| 09:00 - 09:15 | Lecture (Lionel Lapierre, Univeristy of Montpellier) | | | MARCH 1 Lecture | | | | MAROB 1 INNOVAMARE | | | | | | | | | MARBIO 1 | | | | |
| 09:15 - 09:30 | | | | | | | | | | | | | | | | | Lecture | | | | |
| 09:30 - 09:45 | | | intpenier) | (NTNU-AMOS, Øyvind Ødegård) | | | | INNOVAMARE | | | | Workshop | | s of Data fr | om Marine | (NTNU-AMOS, Aksel Alstad Mogstad) | | | | | |
| 09:45 - 10:00 | MAROB 1 | | | MAROB 1 | | | | MAROB 1 | | | | l | Obsen | vatories | | MAROB 1 | | | | | |
| 10:00 - 10:15 | Lecture | | | Lecture | | | | Lecture | | | | | | | | | Lecture | | | | |
| 10:15 - 10:30 | (Asgeir Sorensen; Jens Einar, NTNU-AMOS) | | | (Ioannis Kyriakides, MARISense) | | | | (Đula Naď) | | | | | | | | | (John Folkesson, KTH) | | | | |
| 10:30 - 10:45 | | | | | | | | | | | | | | | | | | | | | |
| 10:45 - 11:00 | MAROB 1 | | | MARBIO 1 | | | | MAROB 1 | | | | | | | | MARCH 1 | | | | | |
| 11:00 - 11:15 | Lecture | | | Lecture | | | | Lecture | | | | | | | | Lecture | | | | | |
| 11:15 - 11:30 | (Ralf Bachmayer, MARUM) | | | (Francesca De Pascalis;F. Madricardo,ISMAR) | | | | (Andreas Birk) | | | | | | | | (Graham Scott, Wessex Archaeology) MARBIO 1 | | | | | |
| 11:30 - 11:45 | MARCH 1 | | | MAROB 1 | | | | MAROB 1 | | | | | | | | | | | | | |
| 11:45 - 12:00 | Lecture | | | Lecture | | | | Lecture | | | | Workshop on Analysis of Data from Marine | | | | Lecture | | | | | |
| 12:00 - 12:15 | (Bridget Buxton, University of Rhode Island) | | | (NTNU-AMOS Thomas Johansen, Simon Blindheim, Tobias Rye Torben, RenanGuedes | | | | (Jo Eidsvik) | | | | | Obsen | vatories . | | (Nikša Glavić and Nenad Antolović, University of Dubrovnik) | | | | | |
| 12:15 - 12:30 | MAROB 1 | | | MARCH 1 | | | | MAROB 1 | | | | l | | | | MAROB | | | | | |
| 12:30 - 12:45 | | Lec | ture | | Lecture | | | | Lecture | | | | | | | | Lecture | | | | |
| 12:45 - 13:00 | | (Ivan Ste | nius, KTH) | | (Koby Sharvit, Israel Antiquities Authority; Bridget Buxton, URI) | | | | (Kanna Rajan) | | | | | | | | (Oleksiy Kebkal, Konstantin Kebkal) | | | | |
| 13:00 - 14:30 | | | | | | | | | | | | | | | | | | | | | |
| 14:30 - 14:45 | | Company p | resentation | | T2 intro | | | | T4 intro | | | | | | | T5 intro | | | | | |
| 14:45 - 15:00 | | (H | 20) | | (Ilias Alexopoulos, AI Zerocaliber) | | | | (EUMR e-Infrastructures, University of Porto) | | | | 1 | | | | (CNR, InnovaMARE, SWAMP tutorial) | | | | |
| 15:00 - 15:15 | T1 intro | | | T3 intro | | | | Company presentation | | | | | | | | T6 intro | | | | | |
| 15:15 - 15:30 | (KTH) | | (| (Marine Unity Simulator) | | | (Hydromea) | | | | l | | | | (Dan Hayes and Ehsan Abdi, Cyprus-Subsea) | | | | | | |
| 15:30 - 15:45 | Group 3 | Group 3 | Group 3 | | Group 3 | Group 3 | | | Group 3 | Group 3 | Group 3 | |] | | Group 3 | Group 3 | | | | | |
| 15:45 - 16:00 | DEMO | T1 | DEMO | | T2 | T3 | DEMO | | DEMO | DEMO | T4 | | l | | | | T5 | T6 | 77 | | |
| 16:00 - 16:15 | H2O | ктн | Statim | | Al | Simulator | Korkyra | | Hydromea | EvoLogics | EUMR e- | | Workshop on Analysis of Data from Marine | | | | CNR | Cyprus | ADRIATIC | | |
| 16:15 - 16:30 | 1120 | | | | Zerocaliber | Simulator | | | | | Infra | | | | CITE | Subsea | | | | | |
| 16:30 - 16:45 | Group 3 | Group 3 | Group 3 | | Group 3 T2 Al | Group 3 T3 Simulator | DEMO Korkyra | | Group 3 DEMO Hydromea | Group 3 DEMO EvoLogics | Group 3 | | Observatories | | Group 3 | Group 3 | | | | | |
| 16:45 - 17:00 | DEMO | T1 | DEMO | | | | | | | | T4 | | | | | | T5 Cypr | T6 | 77 | | |
| 17:00 - 17:15 | H2O | ктн | Statim | | | | | | | | EUMR e- | | | | | | | Cyprus | ADRIATIC | | |
| 17:15 - 17:30 | 20 | | | | Zerocaliber | | | | | | Infra | | | | | - Inn | Subsea | | | | |
| 17:30 - 17:45 | Group 3 | Group 3 | Group 3 | | Group 3 | Group 3 | | | Group 3 | Group 3 | Group 3 | | l | | | | Group 3 | Group 3 | | | |
| 17:45 - 18:00 | DEMO | T1 | DEMO | | T2 | T3 | DEMO | | DEMO | DEMO | T4 | | l | | | | T5 | Т6 | 77 | | |
| 18:00 - 18:15 | H2O | ктн | Statim | | AI | Simulator | Korkyra | | Hydromea | EvoLogics | EUMR e- | | 4 | | CNR | Cyprus | ADRIATIC | | | | |
| 18:15 - 18:30 | | | | | Zerocaliber | | | | , | Bres | Infra | | L | | | | | Subsea | | | |
| 18:30 - 18:45 | | | | | - | \vdash | | | | | | | | | | - | | | | | |
| 18:45 - 19:00 | | | | | \vdash | \vdash | | | | | | | | | | | | | | | |
| 19:00 - 19:15 | | | | | \vdash | \vdash | | | L | | | | | | | | | | | | |
| 19:15 - 19:30 | | | | L | \vdash | | | L | | | | | | | | | | | | L | |
| 19:30 - 19:45 | | | | | | | | | | | | | | | | | | | | | |
| 19:45 - 20:00 | dinner | | | dinner | | | | dinner | | | dinner | | | dinner and closing ceremony | | | | | | | |
| 20:00 - 20:15 | | | | | | | | | | | | | | | | | | | | | |
| 20:15 - 20:30 | | | | | | | | | | | | | | | | | | | | | |

6. BTS PARTICIPANTS

In 2020, over 130 participants from various fields joined Breaking the Surface.



7. SUPPORTERS

SUPPORTED AND FINANCED BY







Financed in the scope of the project EUMarineRobots – Marine robotics research infrastructure network (GA 731103) which has received funding from the European Union's HORIZON 2020 Research and Innovation Programme.



8. PRESENTATIONS

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<u>LEVERAGING OCEAN DATA HARVESTING BY HETEROGENOUS ROBOTIC ORGANIZATIONS AND AUTONOMOUS VEHICLES AS SENSOR CARRYING PLATFORMS</u> by ASGEIR J. SØRENSEN, JENS EINAR BREMNES

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UNDERWATER ARCHAEOLOGY AT BTS: A DECADE OF INNOVATION by JACOB SHARVIT, BRIDGET BUXTON

TUTORIAL 3 INTRO: <u>MARINE UNITY SIMULATOR</u> by IVAN LONČAR, JURAJ OBRADOVIĆ, LUKA MANDIĆ, NATKO KRAŠEVAC, NIKICA KOKIR, KRISTIJAN KRČMAR, MAK GRAČIĆ

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ADRIATIC by ĐULA NAĐ

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